RE 29133

Edition: 2022-02 Replaces: 2020-08



Directional control valves, direct operated, with electrical position feedback and integrated flow control (IFB Multi-Ethernet)

Type 4WRPQ



- Sizes 6 and 10
- ► Component series 3X
- Maximum operating pressure 280 bar
- ▶ Rated flow 32, 80 l/min ($\Delta p = 5$ bar)



Features

▶ Open

- Integrated, digital flow controller (IFB Multi-Ethernet)
- Bus connection/service interface (Sercos, Ether-CAT, EtherNet/IP, PROFINET RT, VARAN)

Safe

- Internal safety function (can be used up to category 4/PL e according to EN 13849-1)
- CE conformity according to EMC Directive 2014/30/EU

Contents

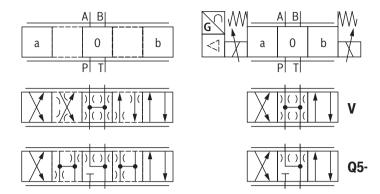
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Ordering code

01	02	03	04	05	06	07		08		09	10	11		12	13	14	15	1	16	
4	WRP	Q				S	-	ЗХ	/		G	F	/	24		D9	0		*	
01	4 main p	orts																		4
02	Direction	nal co	ntrolv	ıalva	direct	oper	atad													WRP
02	Direction	nat co	iitiot v	alve,	unect	opera	ateu													WNF
03	With inte	egrate	d digit	tal flo	w con	trolle	r													Q
04	Size 6																			6
	Size 10																			10
05	Symbols	; poss	sible v	ersior	ı see p	page 3	3													
	flow (Δμ																			
	32l/min				cuge)															32
-	80l/min																			80
Elow (characte	ristic																		
	Progress																			S
			. 0	0 0	0 (00	20								1.		\				04
80	Compon	ent se	eries 3	0 3	9 (30	39:	uncr	anged	insta	llatio	n and d	conne	ction	aimen	sions)				3X
	naterial		rve co	mpati	bility	of sea	ls wit	h hydra	aulic	fluid	used, s	see pa	ge 7)							
⊢	NBR sea																			M \$
	FKM sea	ls																		V
	ure sens				g)															
10	Pressure	ratin	g 280	bar																G
ntern	al press	ure se	nsor	(posit	ion)															
11	In port A	A, B ar	nd P																	F
12	Supply v	oltage	e 24 V																	24
	net inter																			
	EtherNE																			Е
_ F	PROFINE																			N
	Sercos																			S
	EtherCA ⁻	T (CAI	Vopen	profi	le)															Т
	VARAN																			V
_	o to v																			
Conne	ector																			
	Voltage s	supply	, enak	ole ac	knowl	edgm	ent													D9
14	Voltage s				knowl	edgm	ent													D9
14 ressu		or inte	erface		knowl	edgm	ent													D9 0

Notice: ♦ = Preferred type

Symbols



Motice:

Representation according to DIN ISO 1219-1. Hydraulic interim positions are shown by dashes.

Function

General

The **IFB Multi-Ethernet** valve (Integrated **F**ield**b**us) is a digital directional control valve with integrated flow controller, load-independent.

The following operating modes are possible:

- ► Valve direct control
- ► Flow control
- ▶ Pressure/force control
- ▶ Pressure control/flow alternating
- ► Torque/force control/flow
- ▶ Pressure control/valve direct control alternating
- ► Alternating control (flow pressure/force); pQ function (flow-controlled)

Communication is done via the digital Multi-Ethernet interface (X7E1 or X7E2) only. The following data may be exchanged:

- ▶ Command values
- ► Actual values

- ► Configuration and setting of the system control parameters
- ► Status messages, faults or warnings

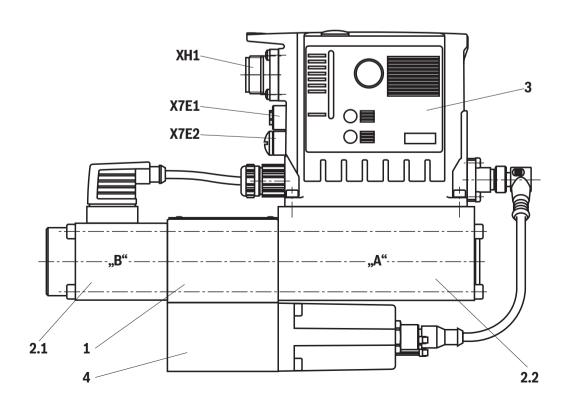
Set-up

The directional control valve with IFB Multi-Ethernet electronics mainly consists of:

- ► Main housing with control spool (1)
- ► Control electronics with integrated fieldbus (3)
 - Connector, voltage supply, safety shut-down (XH1)
 - Ethernet interfaces (X7E1, X7E2)
- ► Pressure sensor sandwich plate (4)
- ► Stroke solenoid (2.1)
- ► Control solenoid with electrical position feedback (2.2)

Motice:

With version "V32", the control spool may rotate in case of single-sided flow through the supply flow edges (P-A or P-B) causing damage to or failure of the valve. This can be solved by reduction of the pressure differential over the supply flow edge to a maximum of 80 bar or by simultaneous use of both control edges (P-A/B-T or P-B/A-T).



Function (flow control)

The integrated electronics (OBE) enables load-independent control of the flow at positive command value by means of the two integrated pressure sensors in ports P and A. At negative command value, the flow is controlled from P to B.

Safety function (only symbol Q5-)

The integrated electronics (OBE) of the valve enable additional shut-off of a channel according to EN 13849-1 in both directions (depending on the symbol, the valve can be considered as safely switched off).

When using symbol V, the valve cannot be used in a safety-relevant manner according to EN 13849-1 while enable acknowledgment always remains 0.

Thanks to the two control solenoids (enable pin D and E, low signal) at the connector (XH1), direction-dependent shut-off is enabled. The control spool of the valve is in spring-centered central position for this purpose (fail-safe position).

Enable acknowledgment pin C for solenoid A and pin F for solenoid B are "high". By connecting both control solenoids (enable pin D and E, high signal), the valve can be controlled by a command value presetting (command value positive, solenoid B or command value negative, solenoid A).

Enable acknowledgment pin C for solenoid A and pin F for solenoid B are "low".

Separate shut-off of solenoid A or solenoid B will moreover allow for the direction-dependent activation or shut-off of the drive.

The integrated electronics (OBE) of the valve enable additional shut-off of a channel according to EN 13849-1 in both directions (depending on the symbol, the valve can be considered as safely switched off). For this purpose, a suitable control system must be provided to perform the plausibility check between the direction-dependent valve signals "enable input" and "enable acknowledgment" (diagnosis signal fed back by the valve) and react in an error case.

When using symbol V, the valve cannot be used in a safety-relevant manner according to EN 13849-1.

Monitoring

The digital control electronics enable comprehensive monitoring functions/error detection including:

- ▶ Undervoltage
- ► Communication error
- ► Cable break for analog sensor inputs
- ► Monitoring of the microcontroller (watchdog)
- ▶ Temperature of the integrated electronics

IndraWorks DS PC program

To implement the project planning task and to parameterize the valve, the user may use the IndraWorks DS engineering tool (see accessories):

- Project planning
- ► Parameterization
- ▶ Commissioning
- ▶ Diagnosis
- ► Comfortable administration of all data on a PC
- ▶ PC operating systems: Windows 10

Motes:

- ► When using symbol V, the enable inputs (enable pin D and E) may only be activated and deactivated together.
- ► For all other symbols, a unilateral shut-off will cause reduced performance data.
- ► 4/3 directional control valves do not have a leakage-free basic locking when deactivated. Leakage must be considered when designing the drive.
- ▶ Valve type 4WRPQ (symbol Q5-) can be used as shut-off element cat. 3 or 4 (up to PL e according to EN 13849-1). For both categories, an additional shut-off element is required to achieve a two-channel shut-off. For further information on the safety application, see operating instructions 29391-B.
- At a flow command value of 0, the specified flow control tolerance also applies.

Technical data

(For applications outside these values, please consult us!)

General					
Size	NG	6 10			
Type of connection		Subplate mounting			
Porting pattern		ISO 4401-03-02-0-05	ISO 4401-05-04-0-05		
Weight	kg	4.7	9.8		
Installation position		any			
Ambient temperature	range	-20 +60			
Storage temperature	range (with UV protection) °C	+10 +40			
Transport temperatur	e range °C	-30 +80			
Maximum storage tim	e years	1 (if the storage conditions are observed, refer to the operating instructions 07600-B)			
Maximum relative hur	midity (no condensation) %	95			
Maximum solenoid su	urface temperature °C	150 (individual operation)			
MTTF _d value according	g to EN ISO 13849 years	150 (for further details see data sheet 08012)			
Can be used up to ca	tegory according to EN ISO 13849-1	3 or 4 (up to PL e); as shut-off element (not symbol V)			
Vibration resistance	► Sine test according to DIN EN 60068-2-6	10 2000 Hz/maximum of 10 g/10 cycles/3 axes			
	▶ Noise test according to DIN EN 60068-2-64	20 2000 Hz / 10 g _{RMS} / 30 g peak / 30 min. / 3 axes			
	► Transport shock according to DIN EN 60068-2-27	15 g / 11 ms / 3 shocks / 3 axes			
Conformity	► CE according to EMC directive 2014/30/EU, tested according to	EN 61000-6-2 and EN 61000-6-3			
	▶ RoHS directive	2011/65/EU ¹⁾			
Protection class acco	rding to EN 60529	IP65 (if suitable and correctly mounted mating connectors are used			

Hydraulic				
Maximum operating	▶ Ports A, B, P	bar	280	
pressure	▶ Port T	bar	200	
Hydraulic fluid			see table page 7	
Hydraulic fluid temperature range (flown-through) °C			-20 +70	
Viscosity range	► recommended	mm²/s	20 100	
	► maximum admissible	mm²/s	10 800	
Maximum admissible degree of contamination of the hydraulic fluid, cleanliness class according to ISO 4406 (c)		Class 18/16/13 ³⁾		
Rated flow $(\Delta p = 5 \text{ bar/c})$	ontrol edge ²⁾)	l/min	32	80

¹⁾ The product fulfills the substance requirements of the RoHS directive 2011/65/EU.

2) Flow for deviating **Ap** (per control edge):

$$q_{x} = q_{Vnom} \cdot \sqrt{\frac{\Delta p_{x}}{5}}$$

3) The cleanliness classes specified for the components must be adhered to in hydraulic systems. Effective filtration prevents faults and at the same time increases the life cycle of the components.

Motice:

The specified technical data were measured with HLP46 and ϑ_{oil} = 40 ± 5 °C.

Technical data

(For applications outside these values, please consult us!)

Hydraulic fluid		Classification	Suitable sealing materials	Standards	Data sheet
Mineral oils	'	HL, HLP, HLPD, HVLP, HVLPD	NBR, FKM	DIN 51524	90220
Bio-degradable	► Insoluble in water	HETG	FKM	100 15000	
		HEES	FKM	ISO 15380	90221
	► Soluble in water	HEPG	FKM	ISO 15380	
Flame-resistant	► Water-free	HFDU (glycol base)	FKM		
		HFDU (ester base)	FKM	ISO 12922	90222
		HFDR	FKM		
	► Containing water	HFC (Fuchs: Hydrotherm 46M, Renosafe 500; Petrofer: Ultra Safe 620; Houghton: Safe 620; Union: Carbide HP5046)	NBR	ISO 12922	90223

Important information on hydraulic fluids:

- ► For further information and data on the use of other hydraulic fluids, please refer to the data sheets above or contact us.
- ► There may be limitations regarding the technical valve data (temperature, pressure range, life cycle, maintenance intervals, etc.).
- ► The ignition temperature of the hydraulic fluid used must be 50 K higher than the maximum surface temperature.
- ▶ Bio-degradable and flame-resistant containing water:
 If components with galvanic zinc coating (e.g. version "J3" or
 "J5") or parts containing zinc are used, small amounts of
 dissolved zinc may get into the hydraulic system and cause
 accelerated aging of the hydraulic fluid. Zinc soap may form
 as a chemical reaction product, which may clog filters,
 nozzles and solenoid valves particularly in connection with
 local heat input.

► Flame-resistant – containing water:

- Due to the increased cavitation tendency with HFC hydraulic fluids, the life cycle of the component may be reduced by up to 30% as compared to the use with mineral oil HLP. In order to reduce the cavitation effect, it is recommended if possible specific to the installation backing up the return flow pressure in ports T to approx. 20% of the pressure differential at the component.
- Dependent on the hydraulic fluid used, the maximum ambient and hydraulic fluid temperature must not exceed 50 °C.
 In order to reduce the heat input into the component, the command value profile is to be adjusted for proportional and high-response valves.

Static /dynamic (valve direct control)		
Hysteresis	%	< 0.25
Range of inversion	%	< 0.05
Response sensitivity	%	< 0.05
Manufacturing tolerance q _{Vmax}	%	< 10
Temperature drift (temperature range 20 °C 80 °C)	%/10 K	Zero shift < 0.25
Pressure drift	%/100 bar	Zero shift < 0.2
Zero compensation		ex plant ±1%

Static /dynamic (flow control)				
Size	NG	6	10	
Flow accuracy 4)	l/min	80±4	180±9	

⁴⁾ Accuracy tolerance of regulated flow/recommended maximum flow

Technical data

(For applications outside these values, please consult us!)

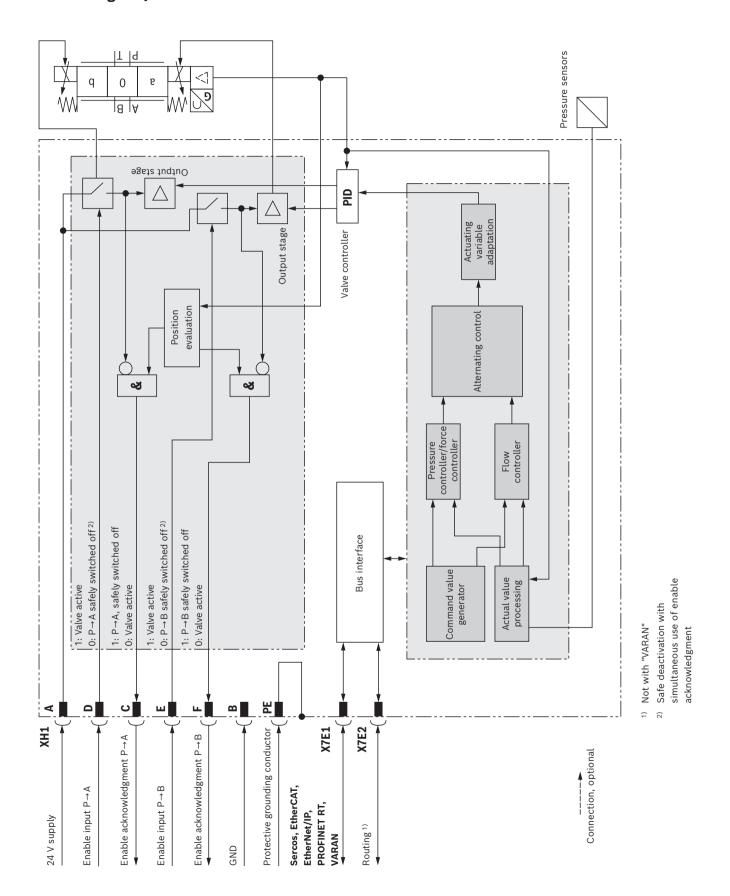
Size		NG	6	10		
Supply voltage ⁵⁾	► Nominal voltage	VDC	24			
	► Minimum	VDC	18			
	► Maximum	VDC	36			
	► Maximum residual ripple	Vpp	2.5 (comply with the absolute su	upply voltage limit values)		
Current consumption	► Maximum ⁶⁾	А	2.5	2.8		
(at nominal voltage)	► Impulse current	А	4	4		
Maximum power consump	tion	W	40	65		
Relative duty cycle		%	100 (continuous operation)			
Fuse protection, external		Α	4, time-lag			
Functional ground and screening			see connector pin assignment (0 page 10	CE-compliant installation)		
Booting time		S	<15			
Switching input	► Quantity		2			
Enable XH1	► Low level	V	/ -3 5			
	► High level	V	15 U B			
	► Maximum current consumption at high level	mA	A <15			
Switching output	► Quantity		2			
Enable acknowledgment	► Low level	V	0 3			
XH1 ⁷⁾	► High level	V	15 U B			
	► Current carrying capacity	mA	50 (short-circuit-proof)			

⁵⁾ Voltage limit values must be observed directly at the connector of the valve (observe line length and cable cross-section!)

⁶⁾ The maximum current consumption will increase when using the sensor inputs or the switching output according to the external load

⁷⁾ The enable acknowledgment outputs must always be loaded with current-consuming switching inputs.

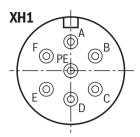
Block diagram/controller function block



Electrical connections, assignment

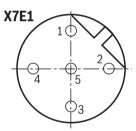
Connector pin assignment XH1, 6-pole + PE according to DIN 43563

Pin	Assignment of interface D9
Α	24 VDC supply voltage 1)
В	GND (reference for pin A, C, D, E, F)
С	Enable acknowledgment 24 VDC (I_{max} = 50 mA) ²⁾ (high \geq 15 V; low <2 V); Flow from P \rightarrow A
D	Enable input 24 VDC (high ≥15 V; low <2 V); Flow from P→A
Е	Enable input 24 VDC (high ≥15 V; low <2 V); Flow from P→B
F	Enable acknowledgment 24 VDC (I_{max} = 50 mA) ²⁾ (high >15 V; low <2 V); Flow from P \rightarrow B
PE	Functional ground (connected directly to metal housing)



Connector pin assignment for Ethernet interfaces "X7E1" and "X7E2" (coding D), M12, 4-pole, socket

Pin	Assignment
1	TxD +
2	RxD +
3	TxD -
4	RxD -
5	Not used



M Notes:

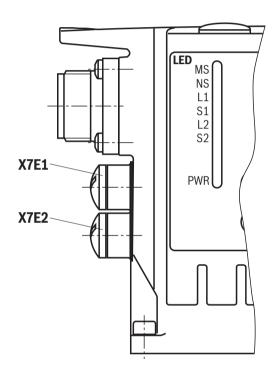
- ▶ Reference potential for all signals: GND
- ► We recommend connecting the shields on both sides via the metal housings of the plug-in connectors.
- ► Using connector pins will affect the effectiveness of the shielding effect. Internal screens are not required.

 $^{^{1)}\,}$ A load increases the current consumption on pin A

²⁾ Enable acknowledgment is issued only if the valve has safely switched off according to EN 13849-1, see operating instructions 29391-B.

LED displays

LED	Interface	Sercos	EtherNET/IP	EtherCAT	PROFINET RT	VARAN
MS		Module status	Module status	Module status	Module status	Module status
NS	Electronics module	S	Network status and others			
L1	X7E1	Link and others	Link and others	Link/activity	Link and others	Link and others
L1 S1	X/EI	Activity and others	Activity and others	not used	Activity and others	Active and others
L2	X7E2	Link and others	Link and others	Link/activity	Link and others	not used
S2	A/E2	Activity and others	Activity and others	not used	Activity and others	not used
PWR	XH1	Power	Power	Power	Power	Power



Displays of the status LEDs

Power LED	Display status			
(LED PWR)	Display Status			
Off	No voltage supply			
Green	Operation			
Module status LED (LED MS)	Display status			
Off	No voltage supply			
Green-red, flashing	Initialization			
Green, flashing	Drive ready for operation			
Green	Drive active			
Orange, flashing	Warning			
Red, flashing	Error			
Green, rapidly flashing	Firmware must be loaded			
Link LED (LED L1)	Display status			
Permanently lit	Cable plugged in, connection established			
Activity LED	Display status			

Motes:

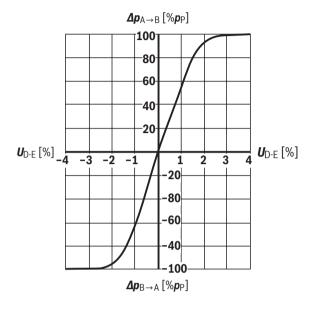
- ► For the connection to the M12 sockets, we recommend using self-locking mating connectors
- ▶ The MS module status LED relates to the electronics module
- ► The NS network status LED indicates the status of the control communication, see application description 30338-FK
- ► LEDs L1, S1, L2 and S2 relate to interfaces "X7E1" and "X7E2"

(LED S1) Flashing

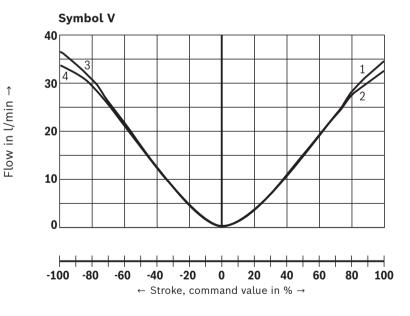
- ► For a detailed description of the diagnosis LEDs, please refer to the functional description Rexroth HydraulicDrive HDx.
- ► Function is only available after start-up of the electronics.

Data sent/received

Pressure/signal characteristic curve (symbol V)



Flow/signal function (rated flow 32 l/min with $\Delta p = 5$ bar/control edge)



1 P-A

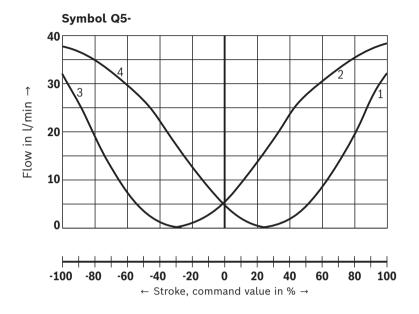
2 B-T

3 P-B

4 A-T

Motice:

Flow/signal function (rated flow 32 l/min with $\Delta p = 5$ bar/control edge)



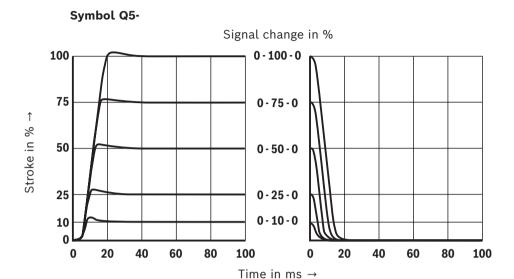
- P-A
 B-T
- **3** P-B
- **4** A-T

Transition function with stepped electric input signals

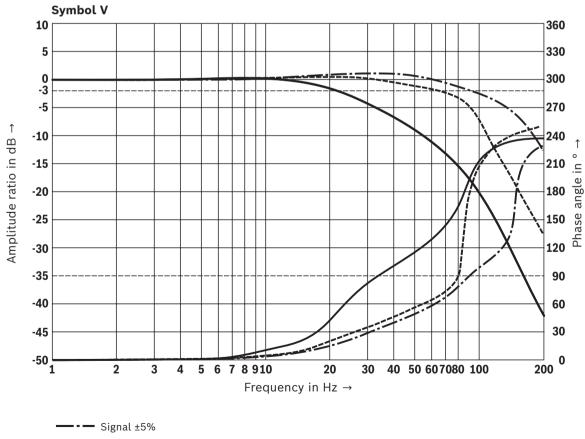
Symbol V Signal change in % 100 0 - 100 - 0 75 0 - 75 - 0 Stroke in % → 50 0 - 50 - 0 25 0 - 25 - 0 0-10-0 10 0 20 40 60 80 100 0 20 40 60 80 100 Time in ms →

Motice:

Transition function with stepped electric input signals



Frequency response



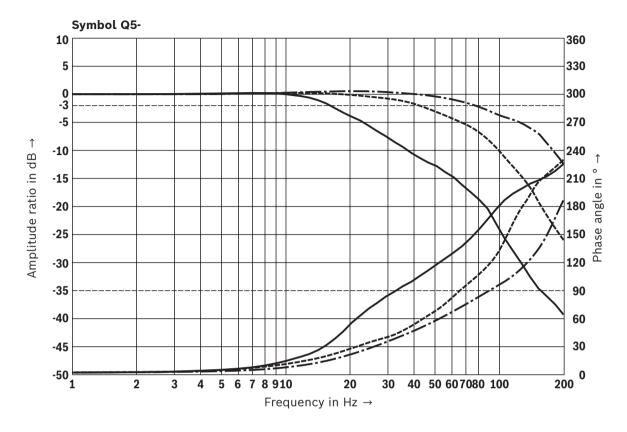
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---- Signal ±25%

—— Signal ±100%

Notice

Frequency response

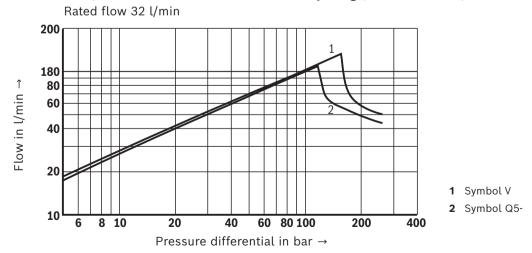


─-- Signal ±5%

---- Signal ±25%

----- Signal ±100%

Flow/load function with maximum valve opening (tolerance ±10%)



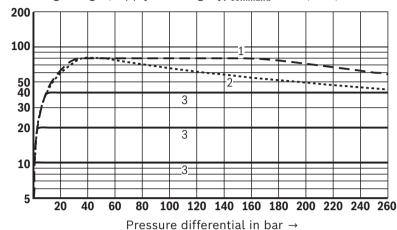
Notice:

Flow in l/min →

Characteristic curves: Size 6 - Flow control (measured with HLP46, θ_{oil} = 40 ±5 °C)

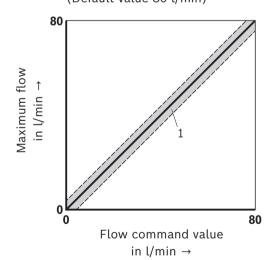
Flow deviation (tolerance ±4 l/min)

Single edge (supply flow edge $q_{V command}$ = 80 l/min)



- 1 Symbol V
- 2 Symbol Q5-
- 3 Symbol V and Q5-

Tolerance of regulated flow / recommended maximum flow (Default value 80 l/min)



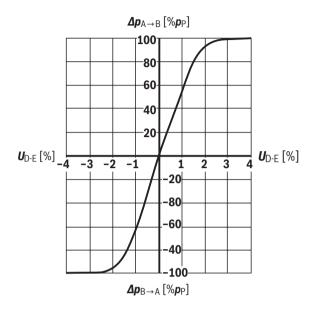
1 Tolerance ±4 l/min

Motice:

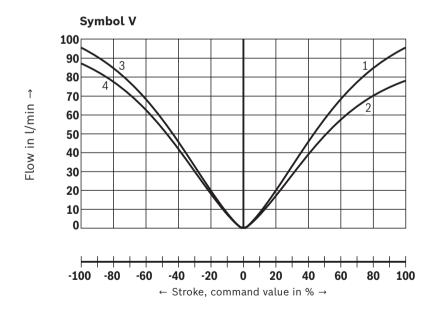
- ► The maximum possible flow is specified in parameter "maximum flow" (P-0-2875.0.3).
- The default value is defined by the performance data of the valve (see parameter description 30330-PA).
- ► Observe the limitations of use of the valve under "Flow/load function with maximum valve opening".

Characteristic curves: Size 10 - Valve direct control (measured with HLP46, $\theta_{\text{oil}} = 40 \pm 5 \, ^{\circ}\text{C}$)

Pressure/signal characteristic curve (symbol V)



Flow/signal function (rated flow 80 l/min with $\Delta p = 5$ bar/control edge)



1 P-A

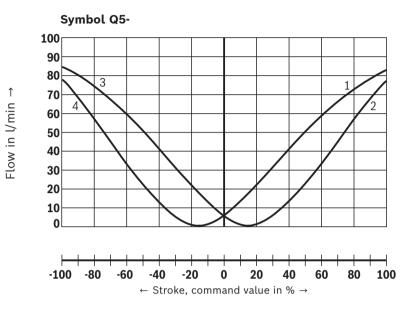
2 B-T

3 P-B

4 A-T

Notice

Flow/signal function (rated flow 80 l/min with $\Delta p = 5$ bar/control edge)



P-A
 B-T
 P-B

4 A-T

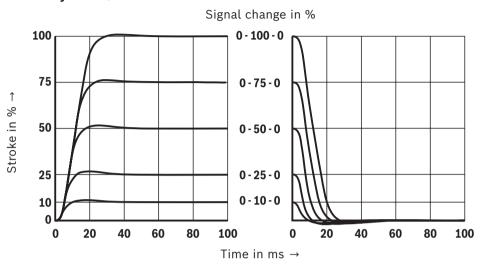
Transition function with stepped electric input signals

Symbol V Signal change in % 100 0-100-0 75 0 - 75 - 0 Stroke in % → **50** 0 - 50 - 0 25 0 - 25 - 0 0-10-0 10 0 20 40 60 80 100 0 20 40 60 80 100 Time in ms →

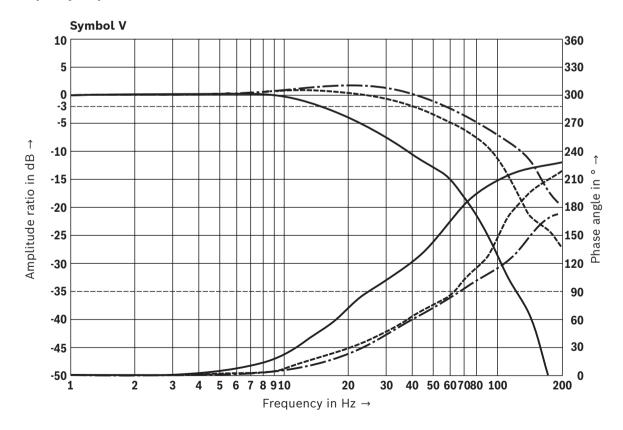
Motice:

Transition function with stepped electric input signals

Symbol Q5-



Frequency response



─-- Signal ±5%

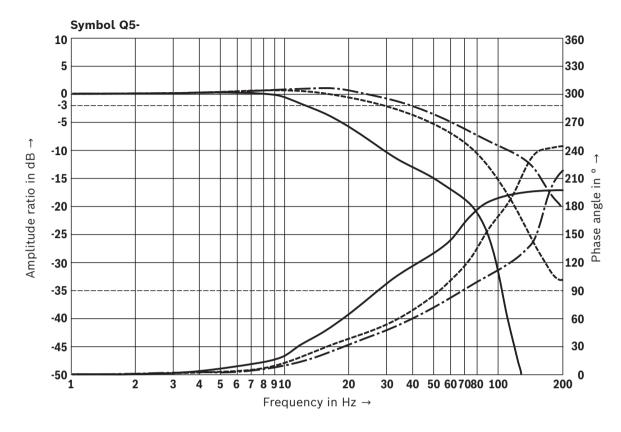
---- Signal ±25%

—— Signal ±100%

Notice:

Characteristic curves: Size 10 - Valve direct control (measured with HLP46, $\theta_{\text{oil}} = 40 \pm 5 \, ^{\circ}\text{C}$)

Frequency response



─-- Signal ±5%

---- Signal ±25%

——— Signal ±100%

Flow/load function with maximum valve opening (tolerance ±10%)

Rated flow 80 l/min 400 200 Flow in I/min → 100 60 40 20 1 Symbol V 2 Symbol Q5-10 60 80 100 8 10 200 400 Pressure differential in bar →

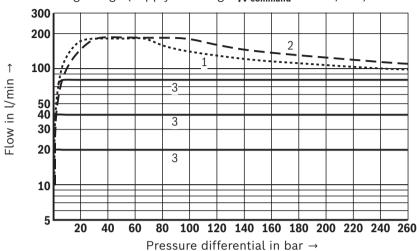
Notice:

Typical characteristic curves which are subject to tolerance variations.

Bosch Rexroth AG, RE 29133, edition: 2022-02

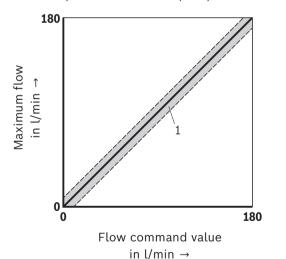
Flow deviation (tolerance ±4 l/min)

Single edge (supply flow edge $q_{V \text{ command}} = 180 \text{ l/min}$)



- 1 Symbol V
- 2 Symbol Q5-
- 3 Symbol V and Q5-

Tolerance of regulated flow / recommended maximum flow (Default value 180 l/min)



1 Tolerance ±9 l/min

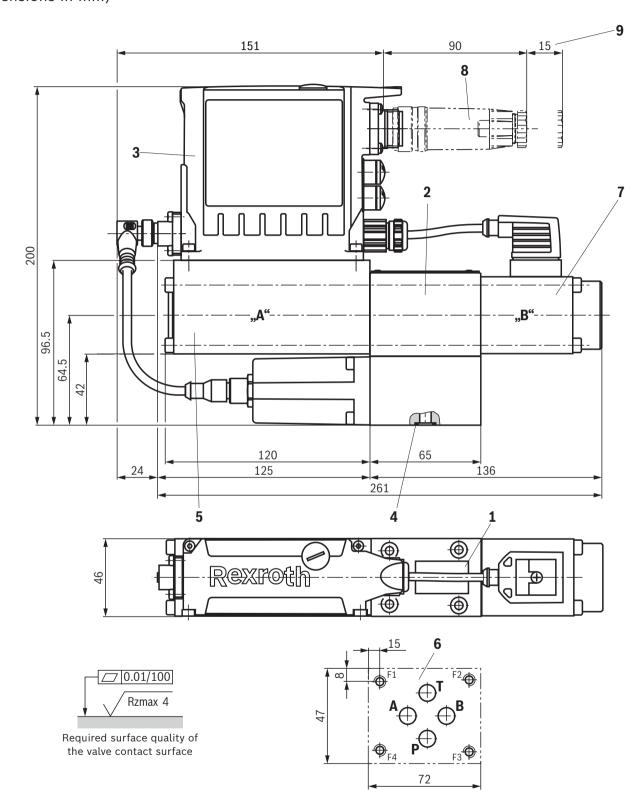
Notice:

► The maximum possible flow is specified in parameter "maximum flow" (P-0-2875.0.3).

The default value is defined by the performance data of the valve (see parameter description 30330-PA).

► Observe the limitations of use of the valve under "Flow/load function with maximum valve opening".

Dimensions: Size 6 (dimensions in mm)

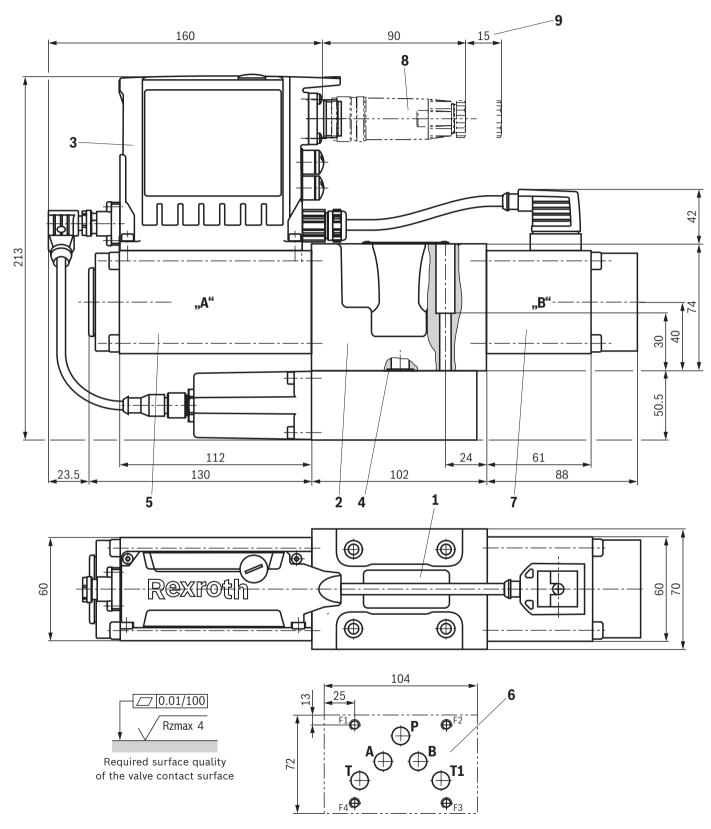




The dimensions are nominal dimensions which are subject to tolerances.

For item explanations, valve mounting screws and subplates, see page 24.

Dimensions: Size 10 (dimensions in mm)



Motes:

The dimensions are nominal dimensions which are subject to tolerances.

For item explanations, valve mounting screws and subplates, see page 24.

Dimensions

- 1 Name plate
- 2 Valve housing
- 3 Integrated digital control electronics
- 4 Identical seal rings for ports A, B, P, T
- 5 Control solenoid with position transducer
- **6** Machined valve contact surface, porting pattern according to ISO 4401-03-02-0-05 (NG6) and ISO 4401-05-04-0-05 (NG10)
- 7 Stroke solenoid
- **8** Mating connectors, separate order, see page 25 and data sheet 08006.
- **9** Space required for removing the mating connector
- 10 Multi Ethernet interface X7E1
- 11 Multi Ethernet interface X7E2

Valve mounting screws (separate order)

Size	Quantity	Hexagon socket head cap screws	Material number		
6	4	ISO 4762 - M5 x 70 - 10.9-CM-Fe-ZnNi-5-Cn-T0-H-B	R913043762		
		Friction coefficient $\mu_{\text{total}} = 0.09 \dots 0.14$; tightening torque $M_A = 8.9 \text{ Nm } \pm 10\%$			
	or				
	4	ISO 4762 - M5 x 70 - 10.9	Not included in the Rexroth		
		Tightening torque M_A = 8.9 Nm ±10%	delivery range		
10	4	ISO 4762 - M6 x 80 - 10.9-CM-Fe-ZnNi-5-Cn-T0-H-B	R913049927		
		Friction coefficient μ_{total} = 0.09 0.14; tightening torque M_A = 13 Nm ±10%			
	or				
	4	ISO 4762 - M6 x 80 - 10.9	Not included in the Rexroth		
		Tightening torque M_A = 13 Nm ±10%	delivery range		



The tightening torque of the hexagon socket head cap screws refers to the maximum operating pressure.

Subplates (separate order) with porting pattern according to ISO 4401-03-02-0-05 (NG6) and ISO 4401-05-04-0-05 (NG10) see data sheet 45100.

Accessories (separate order)

Mating connectors and cable sets

Port	Designation	Version	Short designation	Material number	Data sheet
XH1	Mating connector;	Straight, metal	7PZ31M	R900223890	08006
	for valves with round	Straight, plastic	7PZ31K	R900021267	
	connector, 6-pole + PE	Angled, plastic	_	R900217845	_
	Cable sets;	Plastic, 3.0 m	7P Z31 BF6	R901420483	08006
	for valves with round connector, 6-pole + PE	Plastic, 5.0 m	1	R901420491	
		Plastic, 10.0 m]	R901420496	
		Plastic, 20.0 m	_	R901448068	_
X7E1, X7E2	Cable set; shielded, 4-pole, D coding	Straight connector M12, on straight connector M12, line cross-section 0.25 mm², CAT 5e, length freely selectable (= xx.x)	-	R911172111 ¹⁾	-
	Cable set; shielded, 4-pole	Straight connector M12, on straight connector RJ45, line cross-section 0.25 mm², CAT 5e, length freely selectable (= xx.x)	-	R911172135 ²⁾	_

¹⁾ Additional indication of type designation RKB0040/xx.x



- ► Tighten the M12 connector with a manual torque wrench by 1 Nm.
- ▶ Self-locking M12 cables must be used.
- ► It must be ensured that cables are secured without radial force.
- ► All cables connected to "XH1", "X7E1" and "X7E2" must be bundled in a wire harness after 20 cm the latest. The wire harness must be fixed after further 20 ... 30 cm. Make sure that there is no relative motion between the fixation and the valve.
- ▶ Before the fixation point, there must not be any cable loops.
- ► In general, the information on installation provided by the cable manufacturers must be observed.
- ▶ For further information, see operating instructions 29391-B

Protective cap

Protective cap M12	Version	Material number
		R901075563

Parameterization

The following is required for the p	Material number/download	
1 Commissioning software	IndraWorks, Indraworks D, Indraworks DS	www.boschrexroth.com/IFB
2 Connection cable, 3 m	Shielded, M12 on RJ45, length can be freely selected (= xx.x)	R911172135 (additional indication of type designation RKB0044/xx.x)

²⁾ Additional indication of type designation RKB0044/xx.x

Project planning and maintenance instructions

- ► The supply voltage must be permanently connected; otherwise, bus communication is not possible.
- ► If electro-magnetic interference is to be expected, take appropriate measures for ensuring the function (depending on the application, e.g. shielding, filtration).
- ► The devices have been tested in the plant and are supplied with default settings.
- ► Only complete devices can be repaired.
 Repaired devices are returned with default settings.
 User-specific settings will not be applied. The machine end-user will have to retransfer the corresponding user parameters.

Further information

	High-response/proportional valve with Multi-Ethernet interface	Operating instructions 29391-B
•	Operation fieldbus electronics (xx = software version):	
	- Functional description Rexroth HydraulicDrive HDx-20	30338-FK
	- Parameter description Rexroth HydraulicDrive HDS-16, HDx-17 20	30330-PA
	- Description of diagnosis Rexroth HydraulicDrive HDS-16, HDx-17 20	30330-WA
•	Subplates	Data sheet 45100
•	Hydraulic fluids on mineral oil basis	Data sheet 90220
•	Environmentally compatible hydraulic fluids	Data sheet 90221
•	Flame-resistant, water-free hydraulic fluids	Data sheet 90222
•	Flame-resistant hydraulic fluids – containing water	Data sheet 90223
•	Reliability characteristics according to EN ISO 13849	Data sheet 08012
•	Hexagon socket head cap screw, metric/UNC	Data sheet 08936
•	Installation, commissioning and maintenance of servo valves and high-response valves	Data sheet 07700
•	General product information on hydraulic products	Data sheet 07008
•	Hydraulic valves for industrial applications	Data sheet 07600-B
•	Assembly, commissioning and maintenance of hydraulic systems	Data sheet 07900
•	Information on available spare parts	www.boschrexroth.com/spc
•	"IFB" hydraulic field bus valves	www.boschrexroth.com/ifb

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Notes

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